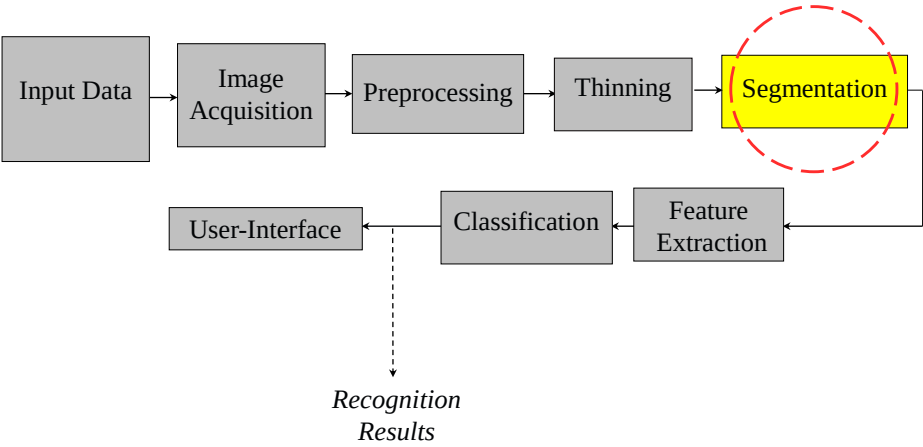


SEGMENTATION

An important step in Image Analysis for Object Recognition

Image Analysis for Object Recognition



What is our object?
*Is it the white
stanchions or the
men?*

*Then accordingly,
what is the
background?*

Now,
John's
example
of
OPTICAL
Illusion



Hence, segmentation is:

- An essential stage to make the problem of image recognition easier to solve.

- And it involves dividing object Image into separate regions, in which the resulting parts has simple characteristic points or features (e.g., brightness, color, texture).

For example, separating the **GREEN WOODS** from the **SKY** and the **LAND** in an image.

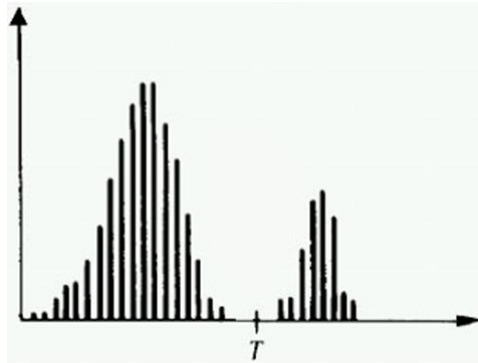
Basic Methods of Image Segmentation

1. Brightness Thresholding

*The function that defines the threshold value
in this method is:*

$$g(x, y) = \begin{cases} 1 & \text{for } f(x, y) \geq T \rightarrow \text{Image pixels} \\ 0 & \text{otherwise } (f(x, y) < T), \rightarrow \text{background} \end{cases}$$

The threshold values are usually taken from the image histogram



Brightness Histogram of the tested object image

Two clear maxima's in the histogram defining the brightness distribution of both the object and the background.

When the threshold value is determined from the WHOLE IMAGE, then we are dealing with GLOBAL THRESHOLD.

However, when the threshold is dependent on the x,y coordinates of the image, then we have DYNAMIC THRESHOLD.

Moreover, when the threshold depends on both image content (i.e., the value of $f(x,y)$) and a certain image feature, $p(x,y)$ say (for example, the image average brightness in some environment), then the threshold is called LOCAL.

We also have multi-level thresholding, in which the level values are

$$T=[T_1, T_2, \dots T_N].$$

As a result, the image is segmented into ***N+1 different brightness levels.***

As an example, the two-level threshold segmentation, we have the following regions:

$$\begin{aligned} R_1: & \text{ gdy } f(x,y) \leq T_1, \\ R_2: & \text{ gdy } T_1 < f(x,y) \leq T_2, \\ R_3: & \text{ gdy } f(x,y) \geq T_2. \end{aligned}$$

Thresholding of brightness can be extended into multi-dimensional thresholding, and hence can be applied to the color images that are encoded in the color representing systems:

RGB (*Red-Green-Blue*)

Or,

HSI (*Hue, Saturation, Intensity*).

The **individual threshold values** can be described on the basis of a three-dimensional histogram – constructed from three color components.

Light Distribution Correction

Light distribution correction of some parts $f(x,y)$ can be done by the aid of **optical or electronical methods**.

For example, to correct the brightness of $f(x,y)$, then knowing the light distribution $g(x,y)$ we can make a brightness correction to:

$$h(x,y) = k * f(x,y) / g(x,y).$$

This of course is a good method when the light distribution does not vary with time.

2. Region Segmentation Approach

Good for images containing some common features like **brightness, color, texture**.

Here, there are two main methods:

- **Region Growing,**
- **Region splitting and merging.**

2. Region Segmentation Approach

a. Region growing

In this method, a primary pixel is considered as a SEED.

The region is growing by adding the neighbours of similar character (color, texture or brightness).

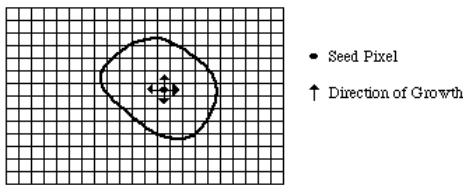
This is done under a condition to be satisfied, for example:

The condition can be verified, for example statistically (probability of existing – scalar product vector ... or by kNN classifiers)

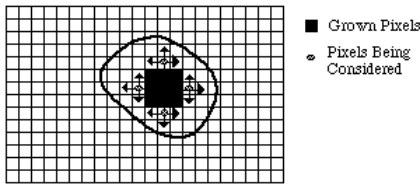
And this is the most difficult task, namely:

*how to select the CRITERION
of similarity between seeds.*

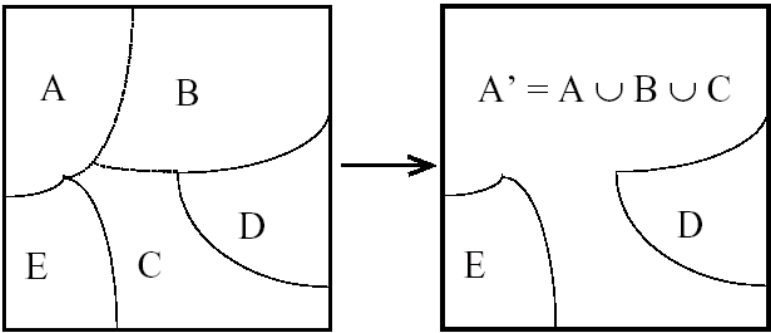
Example of region growing



(a) Start of Growing a Region



(b) Growing Process After a Few Iterations



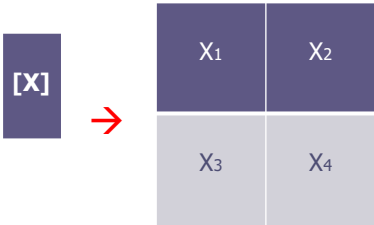
Segmentation by RG

b. Region splitting and merging

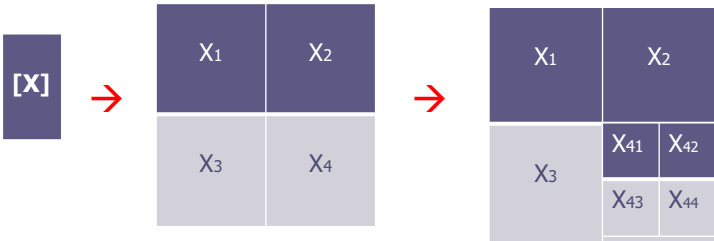
Example of region splitting



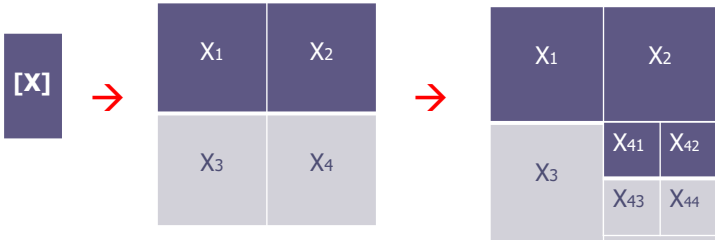
Example of region splitting



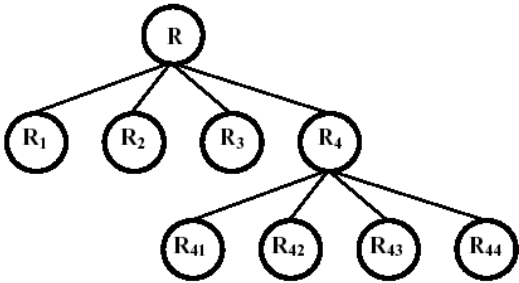
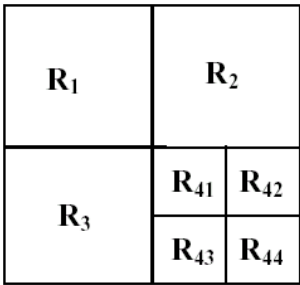
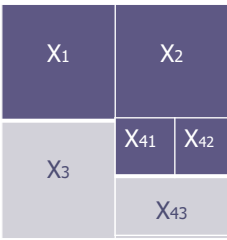
Example of region splitting



Example of region splitting



and merging



3. Segmentation by Template Matching

Before Thinning
Just RECALL
Segmentation by Binarization

Analysis and Processing of Biometric Images

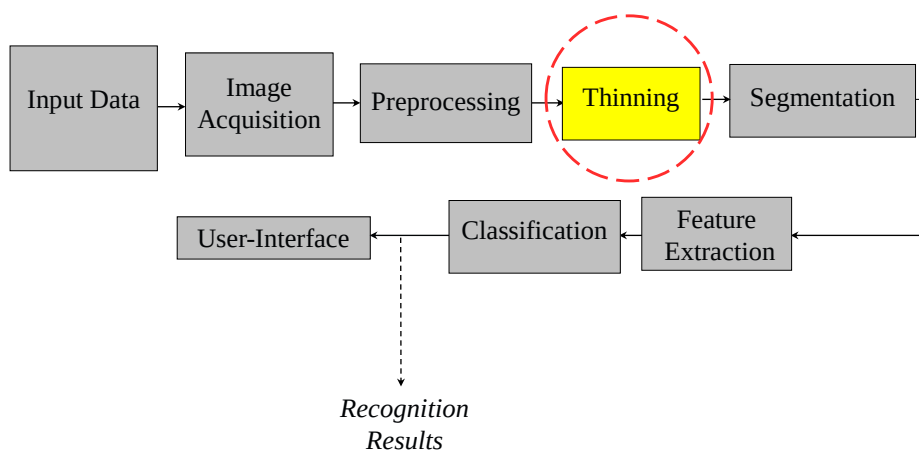
Thinning

Lecture 04

KMM

**Image Thinning
Algorithm**

Image Analysis for Object Recognition

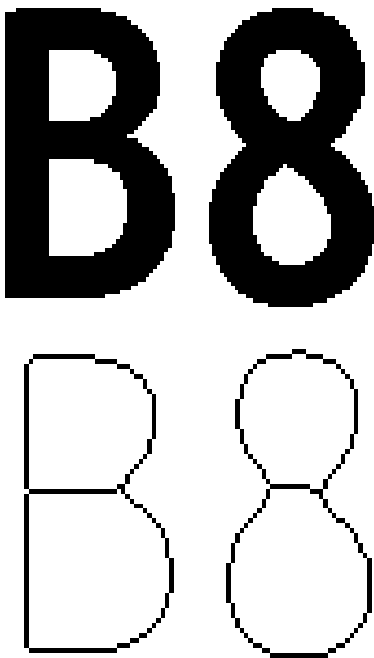


27

Why?

Why thinning

One of the most important reason
for thinning is *image size reduction*,
as can be seen from the following
examples:

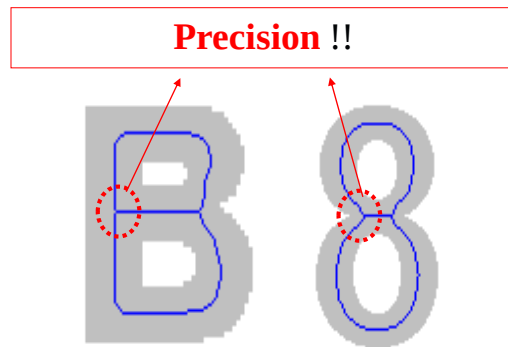




Examples of thinning whole sentences

This is a car.
This is a car.
This is a car.
This is a car.
This is a car.
This is a car.
This is a car.
This is a car.

This is a car.
This is a car.
This is a car.
This is a car.
This is a car.
This is a car.
This is a car.
This is a car.



Clear difference exists
between the letter **B** and the digit **8**

THINNED IMAGE FEATURES

The output of a GOOD thinning algorithm
should be a LINE with:

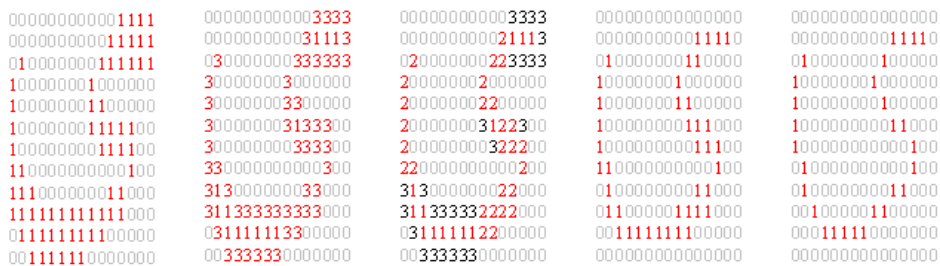
- one-pixel width,
- noninterrupted,
- and centred.

- Thousands of thinning algorithms ...
- In 1967 Blum gave the definition of a ,skeleton’
- The main aim was to reduce the dimension of images.

Examples:

- Rosenfeld’s
- Pavlidis’s
- Zhang’s
- Guo-Hall’s
- Ahmad’s
- Saeed’s
- KMM
-

Exemplary Saeed’s Thinning Algorithm

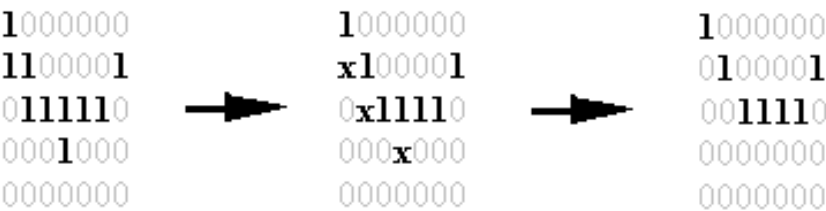


08:15:22

Remove the pixels in such a way that will be left only those which have the following layout:

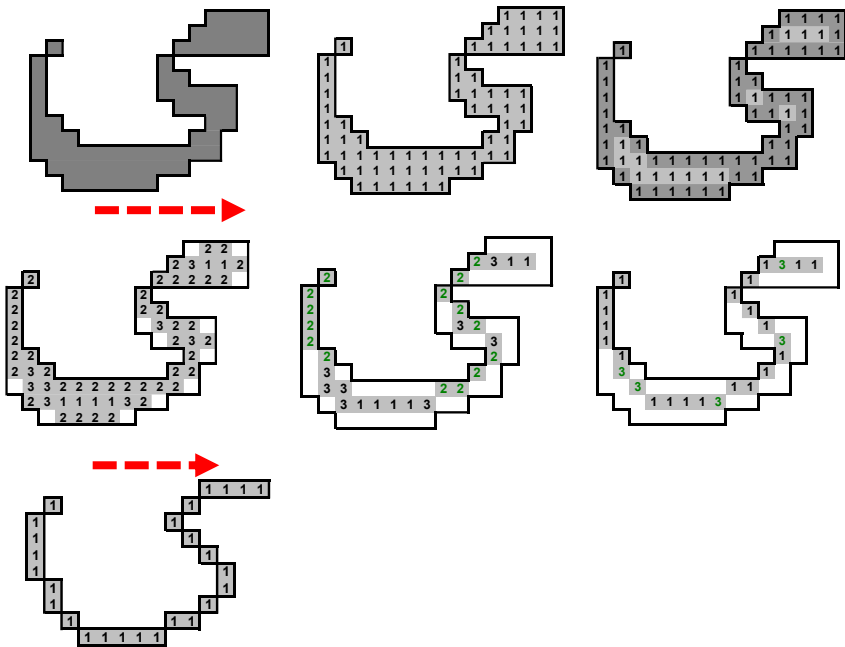
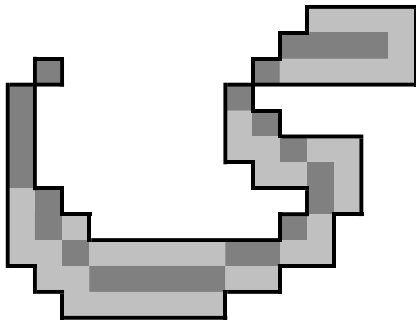


2-pixel line into 1-pixel one:



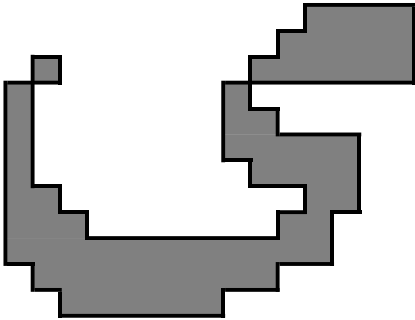
Saeed’s modified Algorithm

KMM Algorithm



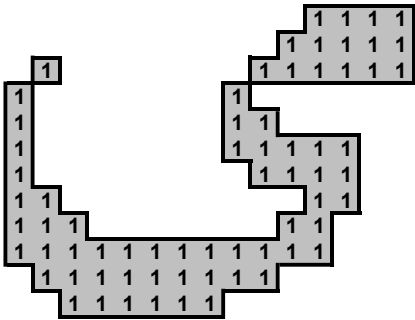
Stages of KMM thinning algorithm

Stage 1



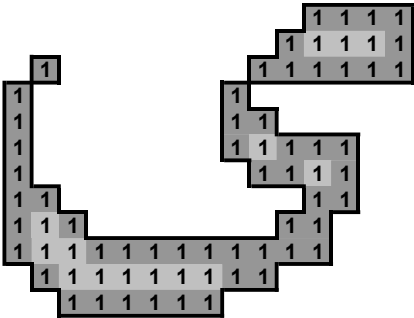
Stage 1

... Image pixels
(the black pixels)
are marked ONES



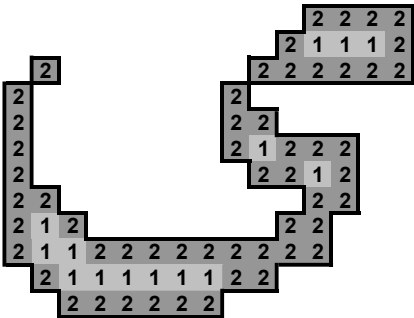
Stage 2

The ONES of direct contact with the background (with the zeros) simultaneously, will form the image contour



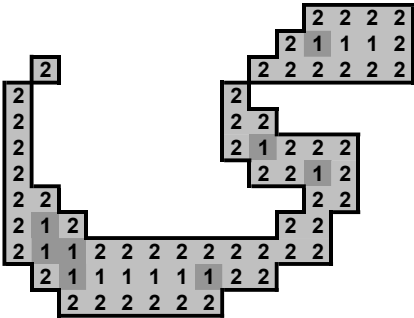
Stage 2

Contour ONES are changed into (marked) '2'



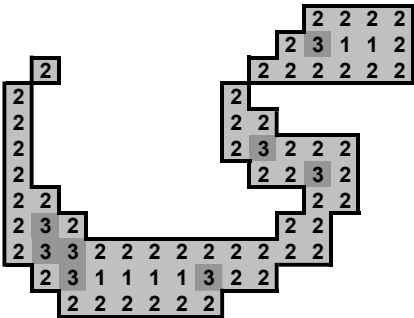
Stage 3

Define the 'elbow
points' –
,Corner points'



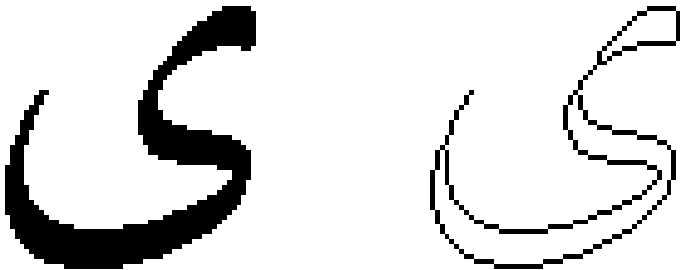
Stage 3

..., and change them
into '3'

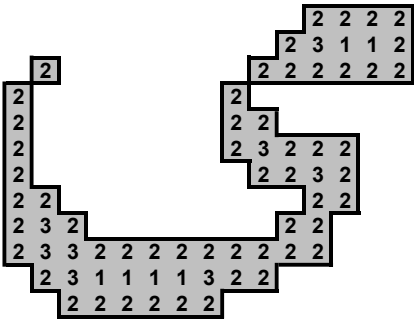


Remark

- This phase may finish the algorithm if the goal is to find the contour.



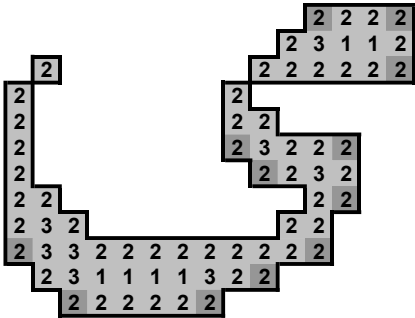
Stage 3 - (contin.)



Extended Version of the Algorithm

■ **Stage 4**

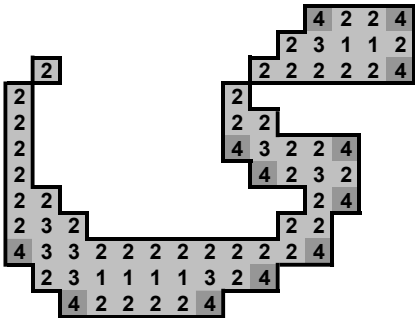
Contour points (2's forming the outline of the tested image) with 2, 3 or 4 neighbors are



Extended Version of the Algorithm

■ **Stage 4**

Contour points (2's forming the outline of the tested image) with 2, 3 or 4 neighbors are changed into 4's



Extended Version of the Algorithm

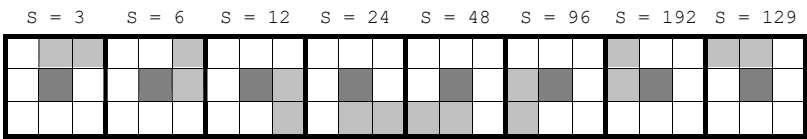
- Notice that there are EIGHT possible configurations for each of the THREE CASES, depending on the distribution of the pixels surrounding the tested pixel x .
- The weight of each neighbouring pixel is taken from the following pixel:

128	1	2
64	x	4
32	16	8

Extended Version of the Algorithm

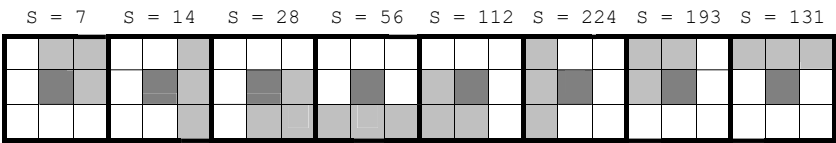
Hence, we have 24 different possibilities:

... with two



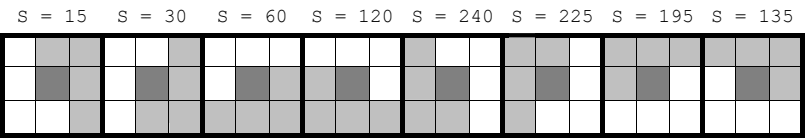
Extended Version of the Algorithm

... with three



Extended Version of the Algorithm

... or with four neighbours

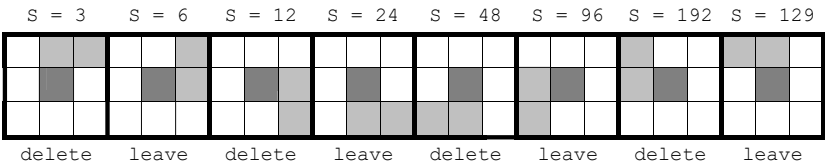


- The sum *s* of the neighbouring pixels within the range 0 to 255, will decide whether to leave or remove (delete/discard) the tested pixel.

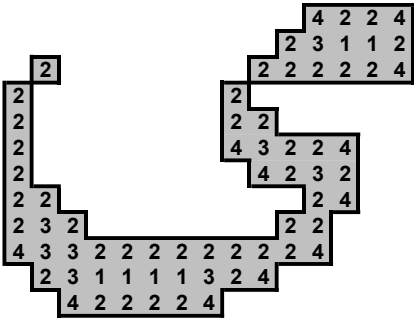
This table is called **Deleting Table**. It presents the SUMS for which the tested pixel should be removed (deleted).

3,	5,	7,	12,	13,	14,	15,	20,
21,	22,	23,	28,	29,	30,	31,	48,
52,	53,	54,	55,	56,	60,	61,	62,
63,	65,	67,	69,	71,	77,	79,	80,
81,	83,	84,	85,	86,	87,	88,	89,
91,	92,	93,	94,	95,	97,	99,	101,
103,	109,	111,	112,	113,	115,	116,	117,
118,	119,	120,	121,	123,	124,	125,	126,
127,	131,	133,	135,	141,	143,	149,	151,
157,	159,	181,	183,	189,	191,	192,	193,
195,	197,	199,	205,	207,	208,	209,	211,
212,	213,	214,	215,	216,	217,	219,	220,
221,	222,	223,	224,	225,	227,	229,	231,
237,	239,	240,	241,	243,	244,	245,	246,
247,	248,	249,	251,	252,	253,	254,	255.

For example, for the pixel with two neighbours:



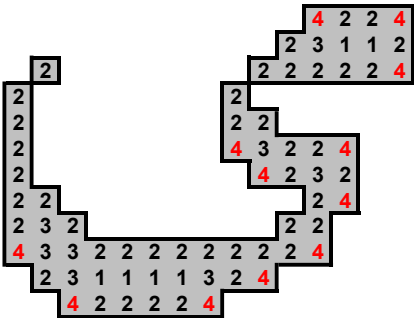
Extended Version of the Algorithm



Extended Version of the Algorithm

Stage 5

Discard the
pixels tabbed
as ‘4’

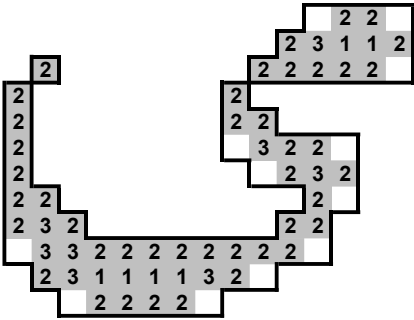


Extended Version of the Algorithm

Stage 5

Discard the
pixels tabbed
as ‘4’

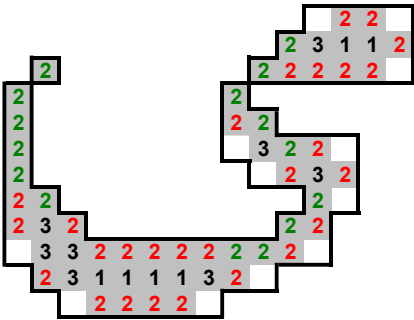
To get → →



Extended Version of the Algorithm

Stage 6

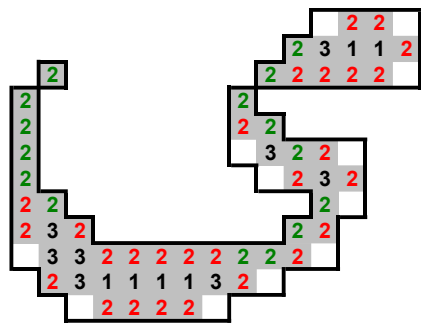
Check all the ‘2’ for
the possibility of
their removal without
losing information
(without causing any
interruption)



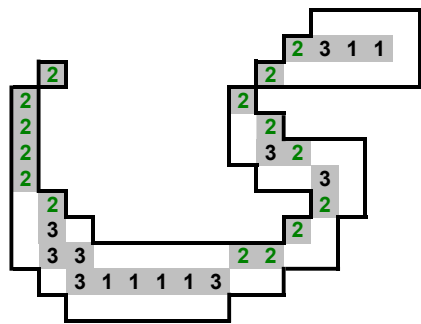
Extended Version of the Algorithm

Stage 6

If possible, remove them.
For example, red **2**'s are to be deleted →



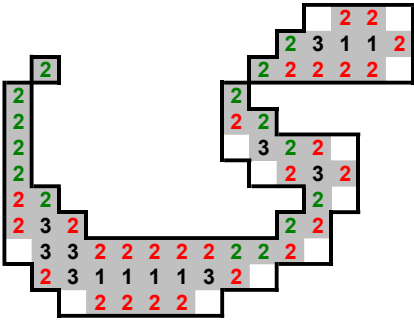
Extended Version of the Algorithm



Extended Version of the Algorithm

Stage 6

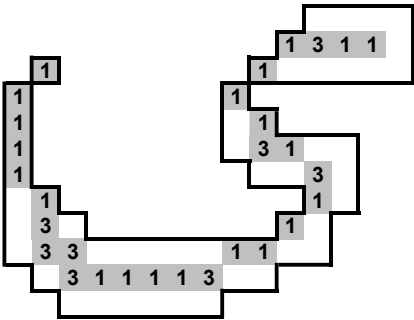
However, if not
(as the case with the
green 2's, ...) →



Extended Version of the Algorithm

Stage 6

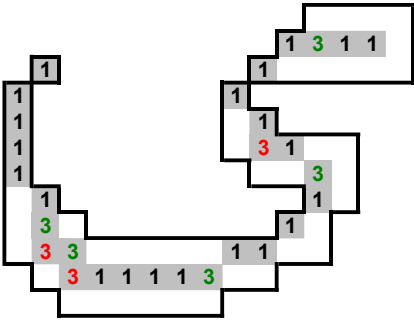
then change them
into 1's



Extended Version of the Algorithm

Stage 7

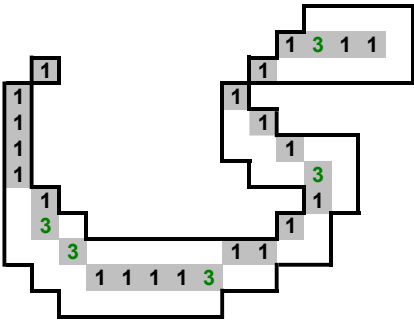
Similar test is repeated, but for the pixels tabbed '3'.



Extended Version of the Algorithm

Stage 7

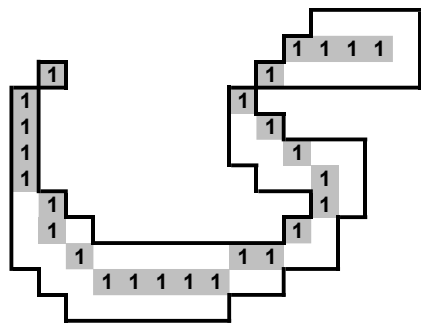
... Delete the pixels according to the Deletion Table.



Extended Version of the Algorithm

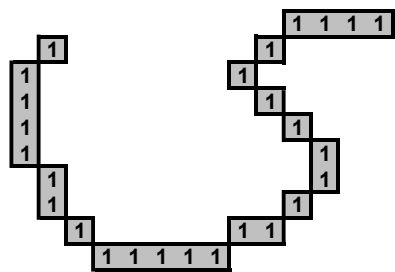
Stage 7

If should left, then
change them into ‘1’



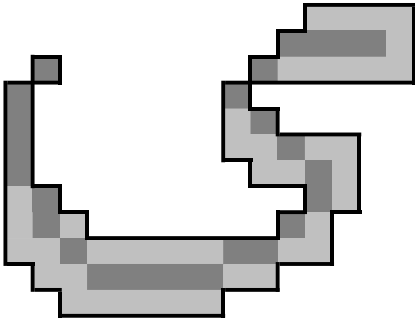
Extended Version of the Algorithm

Repeat stages
2 – 7 as long
as there are
pixels to
remove from
the skeleton



Extended Version of the Algorithm

... until obtaining the final possible image shape:



Comparison with other algorithms



Original image



Guo-Hall's

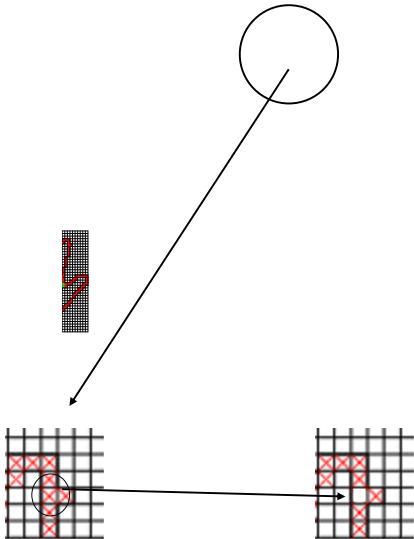
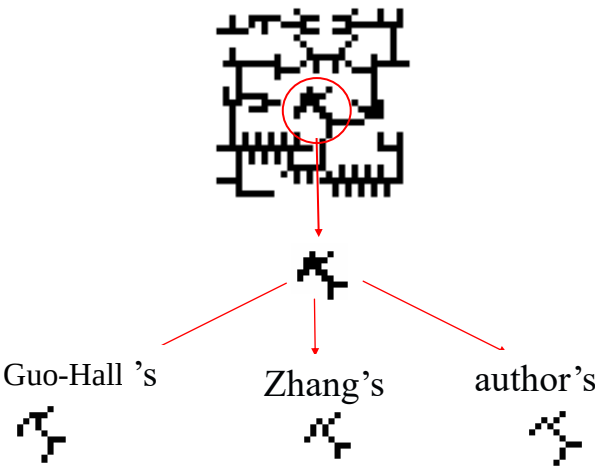


Zhang's

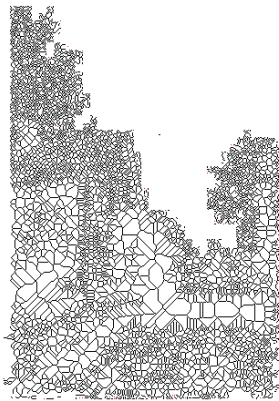


author's

Special considerations



EXAMPLES



Bitmap – more than 2 colours



Bitmap – monochromatic





... by another algorithm, for comparison



Method	Thinned images							
	Bold	<i>Italic</i>						
Guo-Hall's	Bold	<i>Italic</i>						
Zhang's	Bold	<i>Italic</i>						
Ahmed's	Bold	<i>Italic</i>						
Saeed's	Bold	<i>Italic</i>						

Skeletons

Method	image					
						
Guo-Hall's						
Zhang's						
Ahmed's						
author's						

Thank you