COURSE DESCRIPTION CARD

BIALYSTOK UNIVERSITY OF TECHN	OLOGY					Faculty of Electrical E	ngineering
Field of study	Erasmus+ program				Level and form of study	Bachelor Level; Master Level	
A group of modules /specialty						Education profile	general
Course name	Automation Systems	and Ro	botization			Course code Course type	IS-FEE-10087S elective
Course form(s)	ĹC	LC	P SW		s	Semester	Summer
and number of hours	15		15			ECTS credits	3
The programme is valid from						2024/2025	
Introductory courses							
Course objectives	automation Learning pro systems orc	or robot ocedure lered fro	tization system tis for design for integrated	stems for ining auto tors. Intro	r indu omat oduct	strial and service process ion and robotization syste ion to the application of ro	robotization. Analysis of components in selected ses, as well as building automation systems. mms, and creating documentation for newly built obots, and the construction and operation of robotic mulating automated and robotic systems.
Framework programme content	automation, automation. industrial ro social, and and configu systems to/ system. Saf painting, we rehabilitatio of existing s the Factory Introduction PLCSIM Ad technologic control prog the correct (automa Automa botizatio ethical or rations. from the ety of a elding, n n. Spec olutions I/O virtu to prog vance s al line b ram for peratio	ation system ated smart on. Design considerati Transporta robot. Co utomated a naterial cut ialized wc s. Defining al factory ramming p imulator a uilt in the c a PLC cor n of the dig of automat developed	m, contro homes, ing a rob ons. Tec ation in the ntrol of a and robo ting, dos orkshop : requirem environm orogram orogram o	bl enq facto potic s chniqu he im an aud tic sy sing, 1 : Dev nents nent - nable ieme ieme iin Fa nanag odele roboti er pro	pineering, and automation ries, and cities. Compreh system. Non-technical as ues for planning robotizati mediate vicinity of the rol comated and robotic syste stems. Practical applicati esting and inspection, ag eloping the concept of an for key functions and rele for modeling, programm logic controllers (PLC) a ns TIA Portal programmin ctory I/O for a selected pr ing the components of a d production line in Factor zation processes in the for ograms.	automated processes, automatic processes, . Advantages and disadvantages of implementing tensive automation. Automation tools. Service and pects of robotization: economic-organizational, ion. Industry 4.0. Robotic system, its components, bot. Characteristics of automated delivery/retrieval em. Commissioning and startup of a new robotic ions of robots: close-range transport, assembly, priculture and forestry, services, medicine, and a automated (robotic) system based on the analysis evant performance data. Introduction to working with ing, and simulating automated and robotic systems. Ind emulation of system operation using the Siemens ng environment. Configuring components of a rocess, following the adopted concept. Building a production line. Testing the program and verifying ory I/O. Developing technical documentation for the orm of a technical specification for the integrator,
Other information about the course			the c	ourse is	relate	- ed to the scientific activity	conducted at the University

	Student workload related to:	Total number of hours	including contact	including practical
Calculation:	participation in lectures	15	15	
	participation in other forms of activities	15	15	15
	participation in an examination	0	0	
	participation in consultations	3	3	2
	completion of professional training	0	0	0
	preparation for passing a lecture/an examination	12		
	preparation for practical classes	30		30
	Total number of hours:	75	33	47
	Total number of ECTS credits:	3	1,3	1,9
Expected discipline learning outcom	195 	Knowledge	Skills	Social competenc

 Objectives and framework content prepared by
 Ph.D., Eng. Roman Trochimczuk

Date:

Implementation in the academic year

2024/2025

	Lecture					
	Basic concepts: production, production processes, automated processes, automatic processes, automation,					
	2 automation system, control engineering, and automation. Advantages and disadvantages of implementing					
	3 Comprehensive automation. Automation tools. Service and industrial robotization. Designing a robotic system. Non technical aspects of robotization: economic-organizational, social, and ethical considerations. Techniques for					
	4 planning robotization. Industry 4.0.					
	5 6 Robotic system, its components, and configurations.					
	 Transportation in the immediate vicinity of the robot. Characteristics of automated delivery/retrieval systems to/from the robot. 					
	9 10 Control of an automated and robotic system.					
	$\frac{11}{12}$ Commissioning and startup of a new robotic system. Safety of automated and robotic systems.					
	13 Practical applications of robots: close-range transport, assembly, painting, welding, material cutting, dosing, testing					
	14 and inspection, agriculture and forestry, services, medicine, and rehabilitation.					
Programme content	15 Concluding sessions. Passing the lectures.					
	Specialist workshop					
	1 Introductory classes. Developing the concept of an automated (robotic) system based on the analysis of existing					
	2 solutions. Defining requirements for key functions and relevant performance data.					
	3 Introduction to working with the Factory I/O virtual factory environment - for modeling, programming, and simulating					
	4 automated and robotic systems.					

	5	Introduction to programming programmable logic controllers (PLC) and emulation of system operation using the			
	6	Siemens PLCSIM Advance simulator and the Siemens TIA Portal programming environment.			
	7	Configuring components of a technological line built in the digital twin Factory I/O for a selected process, following			
	8	the adopted concept.			
	9				
	10	-Building a control program for a PLC controller managing the components of a production line.			
	11				
	12	Testing the program and verifying the correct operation of the digitally modeled production line in Factory I/O.			
	13	Developing technical documentation for the assumed scenario of automation and robotization processes in the			
	14	form of a technical specification for the integrator, supplemented with developed computer programs.			
	15	Concluding sessions. Passing laboratory classes.			
		Lecture on issues; informational lecture; lecture with multimedia presentation; use of a computer with software.			
Teaching methods site classes)	SW	Practical sessions at computers with engineering software; implementation of the assumed scenario in a specialized workshop.			
Teaching methods	-				
(online classes)	-				
Forms of crediting	L	Written assessment with open-ended questions.			
		Preparation of a report.			
Conditions of crediting	L .	Assessment of responses to open-ended questions in a written exam verifying learning outcomes.			
		Evaluation of reports, assessment of ongoing progress in work, discussions, and participation in classes.			

Outcome symbols	Expected learning outcomes	Expected learning outcomes defined for the field of study						
		Knowlegde	Skills	Social competence				
	Knowledge: the student knows and understands	-						
E1	Correctly defines concepts related to automation and robotization.							
E2	Provides stages and describes the essence of designing systems for the robotization and automation of service, production, industrial processes, as well as building automation.							
E3	Lists and analyzes exemplary systems for the robotization or automation of service, production, industrial processes, as well as building automation; analyzes existing technical solutions							
	Skills: the student can							
	Designs selected systems for robotization and automation using							
E4	chosen computer-aided engineering design environments.							
E5	Is able to integrate computer tools to create a digital twin of a selected automated or robotic process in Factory I/O.							
	Social competence: the student is ready to							
E6	Identifies non-technical aspects of robotic and automation systems.							
Outcome symbols	Methods of verification of learning outcomes	Course for	orm subje	ect to verification				
E1	written assessment	L						
E2	written assessment	L						
E3	written assessment	L						
E4	preparation of reports for the specialized workshop	SW						
E5	preparation of reports for the specialized workshop	SW						
E6	preparation of reports for the specialized workshop	L, SW						
Basic references	Zdanowicz R., Robotyzacja dyskretnych procesów produkcyjnych. Wydawnictwo Politechniki Śląskiej, Gliwice, 2011.							
	2 Marciniak M., Elementy automatyzacji we współczesnych procesach wytwarzania. Oficyna Wydawnicza Politechniki Warszawskiej, Warszawa, 2007.							
	 Mikulczyński T., Samsonowicz Z., Więcławek R., Automatyzacja procesów produkcyjnych. Wydawnictwo Naukowe PWN, Warszawa, 2017. 							
	 Kost G., Łebkowski P., Węsierski Ł., Automatyzacja i robotyzacja procesów produkcyjnych. PWE Polskie Wydawnictwo Ekonomiczne. Warszawa, 2013. 							
	5 Kaczmarek W., Panasiuk J., Robotyzacja procesów produkcyjnych. PWN, Warszawa, 2017.							
Supplementary references	Swider J. red., Sterowanie i automatyzacja procesów technolo, 1 Układy pneumatyczne i elektropneumatyczne ze sterowaniem Śląskiej, Gliwice, 2015.							
	2 Matyszewska E. red. Automatyzacja przemysłu spożywczego Case book. Wydawnictwo Naukowe PWN, Warszawa, 2016.							
	Online databases of scientific journals and scientific publications from the library of Bialystok University of Technology.							
	4 Web service: iAutomatyka.pl, eplan.pl, astor.com.pl, automatykab2b.pl, aps.pl., intechopen.com, Google Patents, Google Scholar.							
	5 Wilson M., Implementation of robot systems: an introduction to integration in manufacturing. Butterworth-Heinemann, 2014.	robotics, automat	ion, and s	uccessful systems				
Course coordinator	Ph.D., Eng. Roman Trochimczuk	Date:		20.02.20				