

Białystok University of Technology, Faculty of Mechanical Engineering									
Field of study	<i>Mechatronics</i>							Degree level and programme type	<i>second-cycle (MSc, Eng) full-time studies</i>
Specialization/ diploma path	<i>Common course</i>							Study profile	<i>academic</i>
Course name	<i>Programming of industrial robots</i>							Course code	<i>IS-FME-00265S</i>
								Course type	
Forms and number of hours of tuition	L	C	LC	P	SW	FW	S	Semester	<i>summer</i>
	15		45					No. of ECTS credits	3
Entry requirements	-								
Course objectives	<i>Getting acquainted with methods of programming industrial robots. Getting to know on-line and off-line robot programming environments. Learning programming languages and acquiring programming skills. Planning and programming movements of manipulators.</i>								
Course content	<i>Lecture: task planning, offline and online programming, Mikro V+ and AS programming languages; description of RobWork and ROS environments, communication between ROS nodes, Rviz module, URDF model. Laboratory: robot task planning (pick and play), programming of an Adept Cobra robot, programming of a Kawasaki robot, compiling and running programs in the ROS environment;</i>								
Teaching methods	<i>Information and problem lecture; Laboratory classes;</i>								
Assessment method	<i>Lecture: one test, Laboratory: evaluation of: self-preparation tests on specified issues before they are discussed during the course, students' reports, students' participation in discussions and their activity during classes.</i>								
Symbol of learning outcome	Learning outcomes Students who successfully complete the course:							Reference to the learning outcomes for the field of study	
LO1	<i>know and understand methods of programming industrial robots</i>							<i>MK2_W02</i>	
LO2	<i>know and understand the concept of programming in the ROS system</i>							<i>MK2_W03</i>	
LO3	<i>can compile and run a program in the ROS environment</i>							<i>MK2_U04, MK2_U06</i>	
LO4	<i>can write programmes controlling manipulator movements</i>							<i>MK2_U06</i>	
Symbol of learning outcome	Methods of assessing the learning outcomes							Type of tuition during which the outcome is assessed	
LO1	<i>Lecture: one test;</i>							<i>L</i>	
LO2	<i>Lecture: one test;</i>							<i>L</i>	
LO3	<i>Laboratory classes: evaluation of: self-preparation tests on specified issues before they are discussed during the course, students' reports, students' participation in discussions and their activity during classes;</i>							<i>LC</i>	
LO4	<i>Laboratory classes: evaluation of: self-preparation tests on specified issues before they are discussed during the course, students' reports, students' participation in discussions and their activity during classes;</i>							<i>LC</i>	
Student workload (in hours)								No. of hours	
<i>Participation in lectures</i>								<i>15</i>	
<i>Participation in laboratory classes</i>								<i>45</i>	

Calculation	Preparation for passing the lecture	25	
	Preparation for laboratory classes	20	
	Preparation for passing the laboratory classes	5	
	Participation in consultations	5	
	TOTAL:	115	
Quantitative indicators		HOURS	No. of ECTS credits
Student workload – activities that require direct teacher participation		65	2.6
Student workload – practical activities		73	2.9
Basic references	1. Kaczmarek W., Panasiuk J., <i>Programowanie robotów przemysłowych</i> . PWN , Warszawa, 2017 2. Kaczmarek W., Panasiuk J., Borys S., <i>Środowiska programowania robotów</i> . PWN , Warszawa, 2017 3. O'Kane J.M., <i>A Gentle Introduction to ROS</i> , online access: https://cse.sc.edu/~jokane/agitr/ , 2018 4. Martinez A., Fernandez E., <i>Learning ROS for Robotics Programming. A practical, instructive, and comprehensive guide to introduce yourself to ROS, the top-notch, leading robotics framework</i>		
Supplementary references	1. Honczarenko J., <i>Roboty przemysłowe: budowa i zastosowanie</i> . WNT, Warszawa, 2010		
Organisational unit conducting the course	<i>Department of Automatic Control and Robotics</i>	Date of issuing the programme	
Author of the programme	<i>Waldemar Kołodziejczyk, PhD, MSc, Eng</i>		24.04.2019
<i>L – lecture, C – classes, LC – laboratory classes, P – project, SW – specialization workshop, FW - field work, S – seminar</i>			