

COURSE DESCRIPTION CARD – SPECIMEN

Faculty of Mechanical Engineering									
Field of study	Mechatronics/Mechanics/Automatics/ Electrotechnics/Control Engineering						Degree level and programme type	Bachelor's degree/Master's degree/Doctoral degree	
Specialization/ diploma path	-						Study profile	-	
Course name	Instrumentation of Control Systems						Course code	IS-MER0022W	
							Course type	obligatory/elective	
Forms and number of hours of tuition	L	C	LC	P	SW	FW	S	Semester	5
	30	-	-	45	-	-	-	No. of ECTS credits	5
Entry requirements	electrotechnics, electronics, electric drive systems, metrology and measurement systems, mechatronics, control engineering								
Course objectives	To know the structure and the operation principles of selected electrical drives (DC and AC), stepper motors, servomotors and their industrial applications. To know the functions, structure, advantages and disadvantages of selected control circuits with contactors, stable and unstable switches, power relays, etc. To acquire the skills in configuring and programming of the selected power inverters. To use electrical drives with rotational and linear modules in modern control systems and industrial applications.								
Course content	Investigations of the DC series motor, 1-phase AC motor capacitor with capacitor, 3-phases AC motor. Operations with computer braking stand. Hand and automatic measurements of the electrical and mechanical characteristics of the selected motors. Investigations of the functions, structure, advantages and disadvantages of the control system instruments. Configuring and programming of the selected power inverters. Electrical drives with rotational and linear modules in modern control systems and industrial applications.								
Teaching methods	lecture, classes, laboratory classes, project, specialization workshop, seminar								
Assessment method	lecture - written tests project - classes active attendance, written report and oral exam								
Symbol of learning outcome	Learning outcomes							Reference to the learning outcomes for the field of study	
LO1	describes, draws and explains the structure and principle of operation of selected electrical drives, power inverters, contactors and power relays								
LO2	applies and programs selected power inverters for simple control systems								
LO3	selects the type and tunes the controller parameters and experiments with the electric control system with rotational and linear modules								
LO4	take measurements hand and automatic measurements of electromechanical quantities, determines static and dynamic characteristics of the motors and electrical drive control systems								
LO5	applies dedicated software in order to engineering project problems								
LO6	uses industrial safety rules and works in a team								

Symbol of learning outcome	Methods of assessing the learning outcomes	Type of tuition during which the outcome is assessed	
LO1	lecture: written tests	L, P	
LO2	project: observation and active attendance in classes, project defence	L, P	
LO3	lecture: written tests	L, P	
LO4	project: observation and active attendance in classes, project defence	L, P	
LO5	lecture: written tests	P	
LO6	project: observation and active attendance in classes, project defence	P	
Student workload (in hours)		No. of hours	
Calculation	lecture attendance	30	
	participation in project classes	45	
	preparation for classes, projects, seminars, etc.	15	
	working on projects, reports, etc.	15	
	participation in student-teacher sessions related to the classes/seminar/project	5	
	implementation of project tasks	4	
	preparation for and participation in exams/tests	4	
	TOTAL:	118	
Quantitative indicators		HOURS	No. of ECTS credits
Student workload – activities that require direct teacher participation		84	3
Student workload – practical activities		34	2
Basic references	1. Isermann R., Mechatronic Systems Fundamentals, Springer, 2005 2. Ogata K., Modern Control Engineering, 4th ed., Pearson Education International, 2002. 3. Dorf R.C., Bishop R.H., Modern Control Systems, 10th Edition, Prentice Hall, 2005. 4. Tewari A., Modern Control Design: With Matlab and Simulink, Wiley-IEEE Press, 2001. 5. Bequette B.W., Process Control, Modeling, Design and Simulation, Prentice Hall, 2003.		
Supplementary references	1. Gieras J. F., Gieras F., Tomczuk B. Z.: Linear synchronous motors: Transportation and automation systems, CRC/Taylor & Francis, 2012 2. Wildi T.: Electrical Machines, Drives and Power Systems, Sixth Edition, Pearson Education International, 2006 3. Górski P: Wzmacniacze operacyjne (in Polish). BTC, Warszawa, 2002. 4. Nawrocki W.: Rozproszone systemy pomiarowe (in Polish). WKŁ, Warszawa 2006. 5. Trybus L.: Regulatory wielofunkcyjne (in Polish). WNT, Warszawa, 1992.		
Organisational unit conducting the course	Department of Robotics and Mechatronics	Date of issuing the programme	
Author of the programme	Mirosław Kondratiuk, PhD Eng.	10.03.2021	

L – lecture, C – classes, LC – laboratory classes, P – project, SW – specialization workshop, FW - field work, S – seminar

Please notice!

Depending on number of students enrolled for the subject hours of tuition are as follows (for each 30 hours given in course description card):

1 – 2 students - 8 hours of tuition hours;

3 – 4 students - 12 hours of tuition;

5 – 6 students - 17 hours of tuition;

7 – 8 students - 21 hours of tuition;

9 and more students - hours of tuition given by a teacher as regular classes.