			F	aculty	of Ele	ctrical	Engin	eering			
Field of study	Electrical and Electronics Engineering and program type						Degree level and programme type	bachelor's degree, full time programme			
Specialization/ diploma path	- Study profile							-			
Course name	Fundamentals of Control Engineering							Course code	IS-FEE-10008W		
Course name	Tu	nuame				gineen	ing	Course type elective Semester winter No. of ECTS credits 6 atics, physics. 6 atics, physics. 6 atics, physics. 6 credits 6 atics, physics. 6 credits 6 atics, physics. 6 credits 6 atics, physics. 6 conly encountered time function an lling of dynamic systems. Transient-relation between transient. tems. The correlation between transient. m. Stability of linear time-invariant structure of control criteria. Quality parameters of control	elective		
Forms and	L	С	LC	Р	SW	FW	S	Semester	winter		
number of hours of tuition	30		30					No. of ECTS credits	6		
Entry requirements	mathematics, physics.										
Course objectives	Introducing students to structures, tasks and methods of analysis and synthesis of simple control systems. Application of different methods of controllers design for control of simple processes										
Course content	Lecture: Laplace transforms of commonly encountered time function and basic Laplace transforms. Mathematical modelling of dynamic systems. Transient-response analysis of first and second-order systems. The correlation between transient and frequency-response and s-plane diagram. Stability of linear time-invariant systems. Hurwitz and Nyquist asymptotic stability criteria. Quality parameters of control on the basis of time and frequency domain performance specifications. Process control and the tuning of three-term controllers (analytical and experimental methods). Discrete time and computer control systems. Analytical techniques required for discrete time system analysis. Design methods for discrete time controllers. Nonlinear systems - practical aspects including relaycontrolled systems (PD and PID compensation). Laboratory class: Basic methods of identification, modelling and control of simple plants. Industry PID controllers, configuration and tuning methods. Control of nonlinear systems (with relay).										
Teaching methods	lecture, laboratory class										
Assessment method	written exam (lecture), evaluation of homework reports (laboratory class)										
Symbol of learning outcome				Lea	arning	outcor	nes Reference to the learning outcomes for the field of study				
LO1	ha	is an e metho	lement ds of s	ary kn imple a	owledg automa	ge of a atic co	nalysis ntrol s	s and synthesis ystem and its			

COURSE DESCRIPTION CARD

	constituent parts;							
	is capable of evaluating the quality specifications of control							
LO2	system and has an elementary knowledge of basic							
	compensation methods of control system;							
1.03	can describe procedures necessary for setting the							
LUJ	parameters of three term controllers							
LO4	has some skills of identification and control of simple plants							
Symbol of		Type of tuition during						
learning	Methods of assessing the learning outcomes	which the outcome is						
outcome		assessed						
L01	written exam, evaluation of reports	L,LC						
LO2	written exam, evaluation of reports	L,LC						
LO3	written exam, evaluation of reports	L,LC						
LO4	evaluation of reports	LC						
	No. of hours							
	lecture attendance	30						
	individual work on lecture topics	30						
	preparation for and participation in exams/tests	15						
Calculation	laboratory class attendance	30						
	preparation for laboratory class	15						
	work on reports	30						
	TOTAL:	150						
	HOURS	No. of ECTS credits						
Student wor	60	2						
	120	4						
Basic references	 1. Ogata K.: Modern control engineering. Prentice-Hall International, 2004. 2. Nise N.S.: Control Systems Engineering, 5th edition, Wiley, 2008. 3. Åström K.J, Murray R.M.: Feedback Systems: An Introduction for Scientists and Engineers, Princeton University Press, 2008. 4. Norman N. S.: Control systems engineering, 5th ed., John Wiley a. Sons, Hoboken 2008. 							
Supplementary	1. Kaczorek T.: Linear Control Systems, vol. 1 and 2, Research Studies Press, 1993.							
references	2. Presentations for lecture (on-line available).							
Organisational		Data of is	cuing the					
unit conducting	Department of Automatic Control and Electronics	progr	amme					
the course								
Author of the	prot. Tadeusz KACZOREK, PhD Eng, Łukasz Sajewski, PhD	08.02.2020						

L – lecture, C – classes, LC – laboratory classes, P – project, SW – specialization workshop, FW - field work,

S – seminar